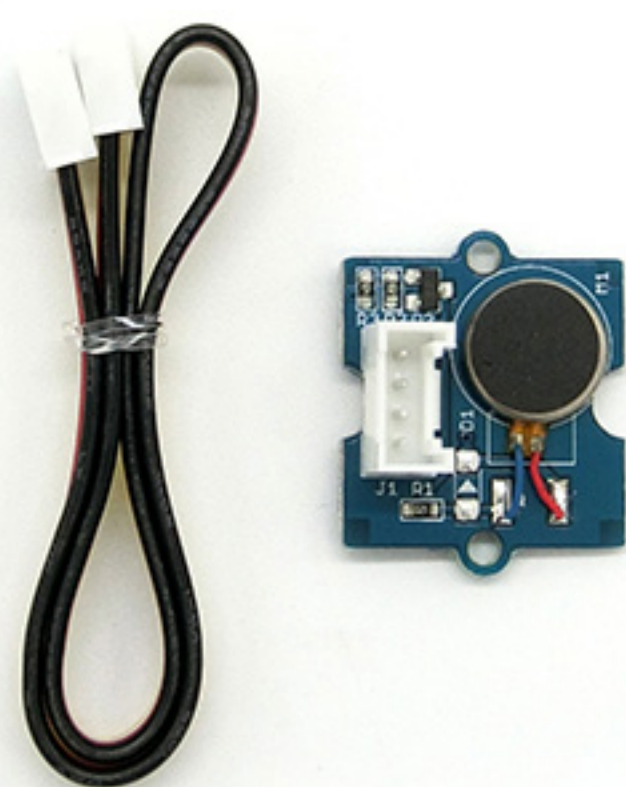


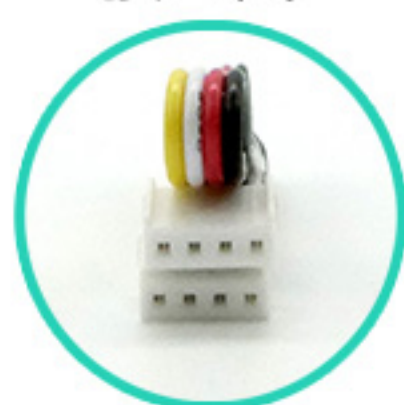


## Grove-Vibration Motor 振動馬達傳感器

兼容Grove  
無聲  
低功耗  
高可靠性

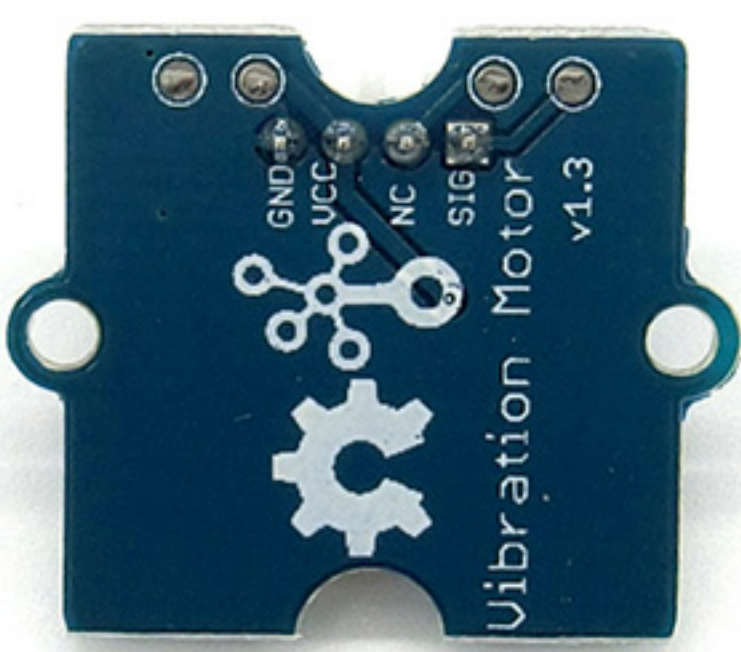


接口圖

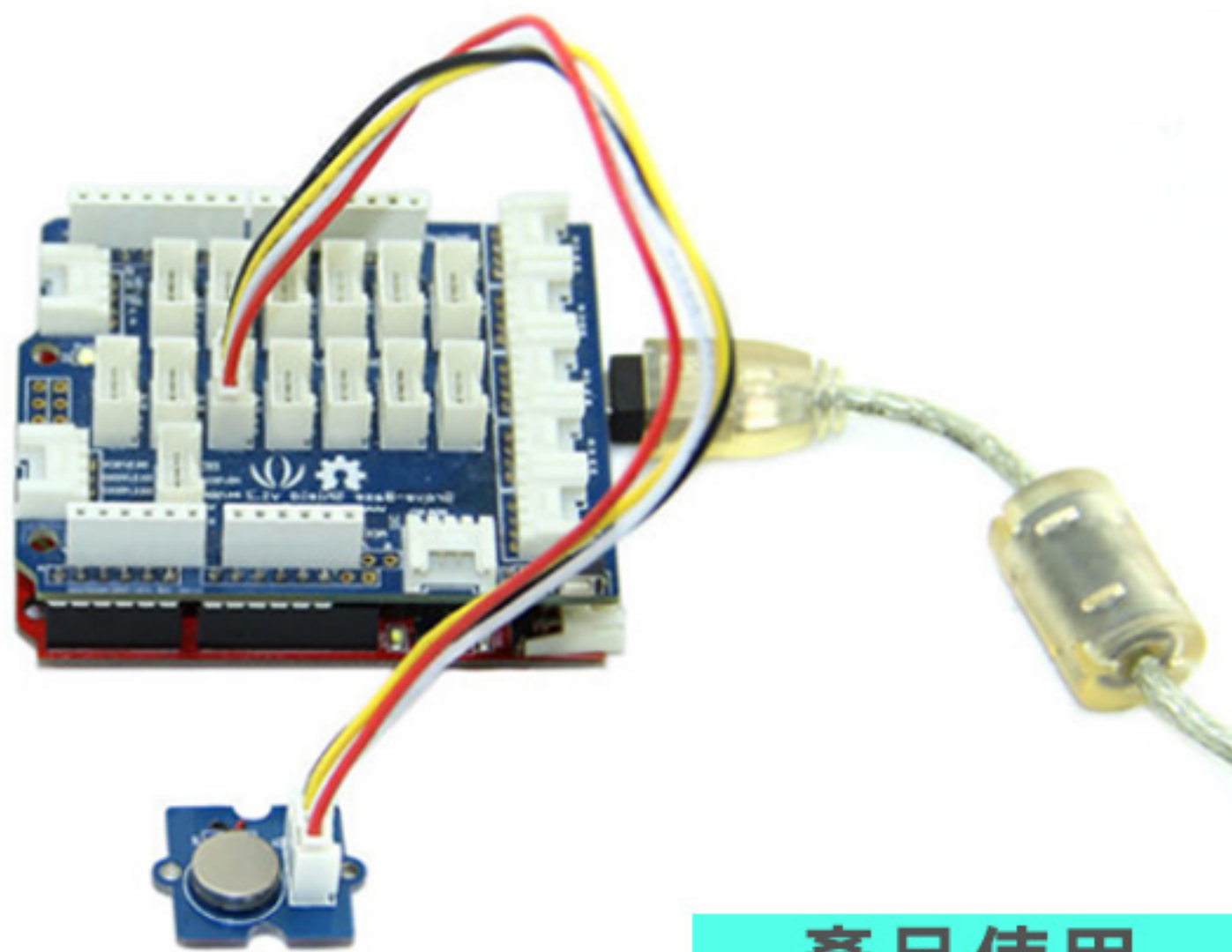


這是一款無聲的迷你震動馬達模組。當輸入高電平時，電機會像手機在靜音模式一樣振動。  
支援 Arduino 與 Raspberry Pi 藍莓派。

### 產品規格



工作電壓：3.0V – 5.5V  
控制模式：邏輯電平  
(高電平電機啟動，低電平電機停止)  
額定轉速：9000 rpm



### 產品使用

讓電機振動像點亮一個發光二極管一樣簡單。示例演示瞭如何讓啟動電機。

1. 用 Grove 接線將電機接到 Grove 基礎擴展板的數字端口 9。
2. 將 Grove 基礎擴展板插到 Arduino 板上。
3. 用 USB 線將 Arduino 連接到電腦。
4. 將下面的代碼複製粘貼到一個新建的 Arduino 文件並載入到 Arduino 中。

```
int MoPin = 9; // vibrator Grove connected to digital pin 9

void setup() {
  pinMode( MoPin, OUTPUT );
}

void loop() {

  digitalWrite(MoPin, HIGH);
  delay(1000);

  digitalWrite(MoPin, LOW);
  delay(1000);
}
}
```

### 藍莓派使用方式

1. You should have got a raspberry pi and a grovepi or grovepi+.
2. You should have completed configuring the development enviroment, otherwise follow here.
3. Connection

- Plug the sensor to grovepi socket D8 by using a grove cable.

4. Navigate to the demos' directory:

```
cd yourpath/GrovePi/Software/Python/
```

- To see the code

```
nano grove_vibration_motor.py # "Ctrl+x" to exit #
```

```
import time
import grovepi

# Connect the Grove Vibration Motor to digital port D8
# SIG,NC,VCC,GND
vibration_motor = 8

grovepi.pinMode(vibration_motor,"OUTPUT")

while True:
  try:
    # Start vibrating for 1 second
    grovepi.digitalWrite(vibration_motor,1)
    print 'start'
    time.sleep(1)

    # Stop vibrating for 1 second, then repeat
    grovepi.digitalWrite(vibration_motor,0)
    print 'stop'
    time.sleep(1)

  except KeyboardInterrupt:
    grovepi.digitalWrite(vibration_motor,0)
    break
  except IOError:
    print "Error"
```

5. Run the demo.

```
sudo python grove_vibration_motor.py
```